TESTING MOTORS

int x, y;

void setup()

{

pinMode(6, OUTPUT);

pinMode(8, OUTPUT);

pinMode(7, OUTPUT);

}

void loop()

{

digitalWrite(8, HIGH);

digitalWrite(7, LOW);

delay(1000);

digitalWrite(8, LOW);

digitalWrite(7, LOW);

delay(500);

//for (x = 1000; x < 2000; x++)

// {

//for (y = 0; y < 10; x++)

// {

digitalWrite(6, HIGH);

delayMicroseconds(2600);

digitalWrite(6, LOW);

delay(20);

// }

// }

}